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Mobile Robotics (Foundations And Trends In Robotics)
By François Pomerleau;Francis Colas;Roland Siegwart**

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Point cloud library - official site

What is it? The Point Cloud Library (PCL) is a standalone, large scale, open project for 2D/3D image and point cloud processing. PCL is released under the terms of

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API review. Proposer: Tim Field. Present at review: Kevin Watts ; Tim Field ; Tully Foote ; Kaijen Hsiao ; API. The Python API in question is implemented here:

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Point Cloud 1.0 is other software developed by Floating Point Solutions Private Limited. Point Cloud is a reverse engineering software to process point clouds.

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